



Project: The Copter Based Greenhouse



Contents and Objectives:

Manual crop mapping and single plant analyzing in greenhouse seem to be time consuming and labor-intensive task. There are issues which are possibly not visible to the naked eyes. Hence one of the solutions to overcome this problem is the use of sensors and multicopters to gather crop information at a low level of height to optimize plant production. On the other hand low altitude flight might affect the plants by altering the environment for instance by creation of wind by the rotating propellers. Vibration of the plants is one of the consequence.

Therefore in this project we want to find out, in which way a multicopter could be used in greenhouse production. Additionally we want to check if the turbulences caused by the copter influences plant growth. For the investigations we use a common small quadrocopter (Perrot Drone) and specific control algorithms. The research takes place in the greenhouses at the Hochschule Osnabrück with different plants. We started our experiments with basil (*Ocimum basilicum*).

Publications:

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